DAE (1<sup>st</sup> Year) MATH-113

## **IMPORTANT—DEFINITIONS**

By: Ali Nawaz Bajwa (M.Phil. (Math), M.Ed.) Mob # : +92(345)6743869 Lecturer in Mathematics Government College of Technology, Sialkot.

## CH # 01---19 E. $\Delta$ Chapter # 02 Chapter #04 What is partial fractions? Define a sequence. 10: 1: (IIA-2017), (IA-2018), (IIA-2019), (IIA-2020) The process, which convert a single Ans. rational fraction, into the sum of two or A set of numbers arranged in order by Ans. more single rational fractions is called some fixed rule is called a sequence. partial fractions. **Examples:** (i) $2, 4, 6, \dots$ (ii) $3, 9, 27, \dots$ 11: Define proper fraction and give one example. 2: Define finite sequence. (IA-2015), (IA-2017), (IIA-2017), (IA-2019), (IIA-2019) (IIA-2018)A fraction in which the degree of the Ans. A sequence is called finite sequence, if it Ans. numerator is less than the degree of the has finite terms. denominator is called proper fraction. **Example:** 2, 4, 6, 8, ..., 50 $2\mathbf{x}$ **Example:** 3: Define infinite sequence. (x-2)(x+5)(IA-2019)Define improper fraction and give one example. 12: A sequence is called infinite sequence, if Ans. (IIA-2015), (IIA-2016) it has infinite terms. Ans. A fraction in which the degree of the **Example:** 4, 6, 8, 10, . . . numerator is greater then or equal to the Define common difference. 4: denominator degree of called is (IIA-2015), (IA-2016) $x^{2} + 1$ improper fraction. Example: The difference between any two Ans. (x+1)(x-1)consecutive terms of an A.P. is called common difference. Chapter # 05 5: Define a series. 13: Define degree and radian measures. (IIA-2016)(IA-2018)The sum of the terms of a sequence is Ans. Degree: If a circle is divided into 360° equal parts, Ans. called a series. then angle subtended by one part at the center of the **Define Arithmetic means (A.Ms).** 6: circle is called a degree. Ans. If a, A, b are three consecutive terms in Radian: Radian is the measure of the angle an A.P., then A is called A.M. of a & b subtended at the center of the circle by an arc, whose and $|A = \frac{a+b}{b}$ length is equal to the radius of the circle. Chapter #07 7: Define a common ratio. 14: Define the law of sines. The Ratio between any two consecutive Ans. (IIA-2015), (IA-2016), (IIA-2016), (IA-2018), (IIA-2020) terms of G.P., is called common ratio. Ans. In any triangle ABC, with usual $\mathbf{r} = \frac{\mathbf{a}_n}{\mathbf{n}}, \ \mathbf{n} > 1$ b ล С **a**<sub>n-1</sub> notations. sinα sinβ $\sin \gamma$ 8: Define geometric means. 15: Define the law of cosines (IIA-2017) (IA-2015), (IIA-2017), (IA-2019) If a, G, b are three consecutive terms in Ans. ABC, with Ans. In any triangle usual a G.P., then G is called G.M. of a and b $\mathbf{a}^2 = \mathbf{b}^2 + \mathbf{c}^2 - 2\mathbf{b}\mathbf{c}\cos\alpha$ i. and $|\mathbf{G} = \pm \sqrt{\mathbf{a}\mathbf{b}}|$ $\mathbf{b}^2 = \mathbf{c}^2 + \mathbf{a}^2 - 2\mathbf{ca}\cos\beta$ notations. Chapter #03 $\mathbf{c}^2 = \mathbf{a}^2 + \mathbf{b}^2 - 2\mathbf{a}\mathbf{b}\cos\gamma$ iii. State Binomial Theorem for positive integer 'n'. 16: Define angles of Elevation and Depression. 9: (IA-2017), (IA-2018), (IIA-2018) (IA-2019)Ans. Angle of elevation: If the line of sight is **Ans.** The rule for expansion of $(a+b)^n$ , where upward from the horizontal, the angle is 'n' is any positive integral power, is called angle of Elevation. called binomial theorem, and defined as: Angle of depression: If the line of sight $(a+b)^{n} = {n \choose k} a^{n}b^{o} + {n \choose k} a^{n-1}b^{1} + {n \choose k} a^{n-2}b^{2} + \dots +$ is downward from the horizontal, the a⁰b¹

angle is called angle of Depression.

** P A P E R - B **					
	Chapter # 08	12:	Define rectangular matrix.		
1:	What is a scalar? Give examples.		(IIA-2018)		
	A scalar is a quantity having magnitude only but no direction.	Ans.	A matrix in which no. of rows and no. of columns are not equal is called rectangular matrix.		
Exam	ples: Length, Mass, Time, Volume, etc.	13:	Define the minor of an element of a		
2:	What is a vector? Give examples.	10.	matrix.		
Ans.	A vector is a quantity having both		(IA-2018)		
Evom	magnitude and direction.	Ans.	If $\mathbf{A} = \begin{bmatrix} \mathbf{a}_{ii} \end{bmatrix}$ is a square matrix of order n,		
	ples: Force, Velocity, Acceleration, etc.		then minor of an element $a_{ii}$ of A is		
	What is a unit vector?		denoted by $\mathbf{M}_{ii}$ is the determinant of		
Ans.	A vector whose magnitude is unity is called a unit vector.				
4:	What are parallel vectors?		order $(n-1, n-1)$ and which is obtained		
	(IA-2019)		by deleting the ith row & jth column of A.		
_	→	14:	Define a co-factor of an element of a		
Ans.	Two vectors $\vec{a}$ and $\vec{b}$ are parallel if	14.	matrix.		
	there exist a non-zero $k \in \mathbb{R}$ , such that		(IIA-2019)		
	$\vec{a} = k\vec{b}$ .	Ans.			
5:	Define scalar product of two vectors.	/	is the minor of element $\mathbf{a}_{ij}$ is called the		
	(11A-2018)		cofactor of element $\mathbf{a}_{ij}$ .		
Ans.	The scalar product of two vectors		, ,		
	$\vec{a} \ll \vec{b}$ is denoted by $\vec{a} \cdot \vec{b}$ and defined		Chapter # 10		
	as $\vec{\mathbf{a}} \cdot \vec{\mathbf{b}} =  \vec{\mathbf{a}}   \vec{\mathbf{b}}  \cos \theta$	15:	Define plane figures.		
6:	Define vector product.		(IIA-2015), (IA-2019)		
	(IA-2016), (IA-2018)	Ans.	Those figures which occupy an area with		
Ans.	The vector product of two vectors		only two dimensions are called plane		
	$\vec{\mathbf{a}} \ \& \vec{\mathbf{b}}$ is denoted by $\vec{\mathbf{a}} \times \vec{\mathbf{b}}$ and is		figures.		
	defined as $\vec{a} \times \vec{b} =  \vec{a}   \vec{b}  \sin \theta \hat{n}$ .	<b>16:</b>	Define a triangle.		
	Chapter # 09		A plane figure bounded by three straight lines is called a triangle.		
7:	Define row and column matrices.	17:	Define Isosceles triangles.		
	(IA-2017)		(IA-2015), (IA-2018), (IIA-2020)		
Ans.	A matrix has only one row is called <b>row</b>	Ans.	A triangle whose two sides are equal and third side is different is called		
_	matrix.		Isosceles triangle.		
	A matrix has only one column is called	18:	Define equilateral triangle.		
	column matrix.		(1A-2016)		
8:	Define identity matrix.	Ans.	A triangle whose all sides are equal in		
Ans.	(IA-2019) A diagonal matrix in which all diagonal		length is called equilateral triangle.		
	elements are 1 is called identity matrix.		Chapter # 11		
9:	Define symmetric matrix.	<b>19:</b>	Define a quadrilateral.		
	(IA-2015)	Ans.	A plane figure bounded by four straight		
Ans.	A square matrix A is said to be		lines is called a quadrilateral.		
	symmetric if $A^t = A$ .	20:	Define a rhombus.		
10:	Define diagonal matrix.	Α.	(IIA-2017)		
	(IA-2016), (IIA-2016), (IA-2018)	ANS.	A quadrilateral having all sides are equal with unequal diagonals.		
Ans.	A square matrix in which all elements except diagonal elements are zero is	21:	Define a cyclic quadrilateral and write		
	called diagonal matrix.		its area.		
11:	Define scalar matrix.	_	(1A-2017)		
	(IIA-2017), (IIA-2020)	Ans.	A quadrilateral inscribed in a circle		
Ans.	A diagonal matrix in which all diagonal		is known as a cyclic quadrilateral.		
	elements are same is called scalar		Area = $\sqrt{(s-a)(s-b)(s-c)(s-d)}$		
	matrix.				

Chapter # 12		Chapter # 15			
22:	Define a polygon.	33:	Define polygon prism.		
	(IA-2019)		(11A-2014)		
Ans.	A plane figure bounded by a finite number of straight lines is called	Ans.	A prism with a polygon base is known as		
	polygon.		polygon prism.		
23:	Define a regular polygon.		Chapter # 16		
Ans.	A polygon is said to be regular, when all its sides and angles are equal.	34:	Define cylinder.		
24:	Define inscribed polygon	Ans.	straight line moving parallel to its original		
(14	(circumscribed circle). -2015), (11A-2015), (11A-2016), (1A-2018), (11A-2020)		position, while its end describes a closed figure in a plane.		
Ans.	If a circle passes through the corners of	35:	Define hollow circular cylinder.		
	a polygon, then this polygon is called	33.			
25.	inscribed polygon.   Define circumscribed polygon	<b>A</b>	(IIA-2018)		
25:	Define circumscribed polygon (inscribed circle) (IA-2017), (IIA-2018)	Ans.	The space between two concentric cylinders is called Hollow Circular Cylinder.		
Ans.		36:	Define Elliptic cylinder.		
	that every side of the polygon touches the circle, then this polygon is	Ans.	The cylinder with a base, is an ellipse is		
	called circumscribed polygon.		called an elliptic cylinder.		
	Chapter # 13	27.	Chapter # 17		
26:	Define a circle.	37:	Define pyramids.		
Ans.	The set of points whose distance from a fix point is constant.	Ans.	(IIA-2017), (IA-2019), (IIA-2019) A pyramid is a solid, whose base is a		
27:	Define diameter of a circle.		plane polygon and sides being triangles		
	(IIA-2018)		that meet in a common vertex.		
Ans.	A chord passing through the center of the circle is called a diameter.		Chapter # 18		
<b>28:</b>	Define chord of a circle.	38:	Define cone.		
Ans.	A line segment whose end points are any two points of a circle is called a chord of the circle.	Ans.			
29:	What are concentric circles.		line, one end of which is fixed and the other end describes a closed curve in a		
	(IIA-2019)		plane.		
Ans.	The circles with common center are called concentric circles.		Chapter # 19		
30:	Define a sector of the circle.	<b>39:</b>	Define sphere.		
Ans.	A part of a circle, lie between two radii and arc of circle.	<b>A</b> 19 0	(IA-2019)		
31:	Define a segment.	Ans.	A sphere is a solid bounded by a closed surface, every point of which is		
Ans.	A part of a circle which is cut off by a straight line not passing through the		equidistance from a fixed point called the Centre.		
	center.	40:	Define spherical shell.		
	Chapter # 14		(11A-2019)		
32:	Define irregular figure.	Ans.			
Ans.	A figure which is not uniforms and regular in shape is called irregular figure.		two concentric spheres of different radius.		
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