## Bright Career Science Academy Narowal Important Definitions "Calculus & Analytic Geometry" (Math-12)

Chapter No. <1> Function: A function is rule relating two sets in such a way that each element in the first set corresponds to one and only one element in the second set. **Polynomial Function:** A function of the form  $P(x) = a_0 x^0 + a_1 x^1 + a_2 x^2 + \dots + a_{n-1} x^{n-1} + a_n x^n$  is called polynomial function where  $n \in W \text{ and } a_0, a_1, a_2, \dots, a_n \in R.$ **Linear Function:** A function of the form f(x) = ax + b where  $a, b \in R$  and  $a \neq 0$  is called linear function. **Identity Function:** A function of the form f(x) = x is called Identity function. **Constant Function:** A function of the form f(x) = c where  $c \in R$  is called constant function. **Rational Function:** A function of the form  $\frac{P(x)}{Q(x)}$  where P(x) and Q(x) are polynomials and  $Q(x) \neq 0$  is called rational function. **Exponential Function:** A function in which variable appear as power of a constant is called exponential Function.  $E \cdot g \cdot y = 2^x$ ,  $y = e^x$ . **Logarithmic Function:** The functions  $f(x) = \log a^x$  and  $f(x) = \log e^x$  are called general and natural logarithmic function respectively. **Explicit Function:** If y is easily expressed in term of x then y is called an explicit function. E.g.  $y = x^2 + 3x$ ,  $y = \sqrt{x^2 + 1}$ . **Implicit Function:** If y is not expressed in term of x then y is called an implicit function. E.g.  $x^2 + xy + y^2 = 4$ . **Even Function:** A function f(x) is said to be an even function if f(-x) = f(x). **Odd Function:** A function f(x) is said to be an odd function if f(-x) = -f(x). Parametric Function: A function in which x and y are expressed as functions of a third variable is called parametric function. **Inverse Function:** Let f(x) be a bijective function from A to B then its inverse is  $f^{-1}(x)$  which is onto function from B to A. **Limit Of A Function:** Let f(x) be a function if the value of f(x) tend to a fixed number "L" as x tends to a then "L" is called limit of f(x) as x tends to a. It is written as  $\lim_{x \to a} f(x) = L$ . BCSA **Continuous Function:** A function f(x) is said to be continuous at x = c if: (i) f(c) is defined (ii)  $\lim f(x)$  exists (iii)  $\lim f(x) = f(c)$ . Discontinuous Function: Any function which is not continuous is called discontinuous function. Sandwich Theorem: Let f, g and h be functions such that  $f(x) \le g(x) \le h(x)$ , If  $\lim_{x \to \infty} f(x) = L$  and  $\lim_{x \to \infty} h(x) = L$  then  $\lim_{x \to \infty} g(x) = L$ . Chapter No. <2> Derivative: The rate of change of a function with respect to independent variable is called Derivative. **OR** The derivative of a function y = f(x) with respect to x is denoted by  $\frac{dy}{dx}$  or f'(x) defined as  $\frac{dy}{dx} = \lim_{\delta x \to 0} \frac{\delta y}{\delta x} = \lim_{\delta x \to 0} \frac{f(x + \delta x) - f(x)}{\delta x}$ . Point Of Inflection: A point at which the function has neither maximum nor minimum value is called point of inflection **Critical Point:** If f'(c) = 0 or f'(c) does not exist then the point (c, f(c)) is called critical point of f(x). **Stationary Point:** Those critical points of f(x) at which f'(x) = 0 are called stationary points of f(x). **Increasing Function:** A function f(x) is called increasing function if f'(x) > 0 for all  $x \in (a, b)$ . **Decreasing Function:** A function f(x) is called decreasing function if f'(x) < 0 for all  $x \in (a, b)$ . Graphical Meaning Of Derivative: Graphical meaning of derivative is the slope of tangent line to the graph of function at given point. Chapter No. <3> Integration or Anti-derivative: The process of finding anti derivative is called integration. **OR** A function F(x) is an anti-derivative of a function f(x) if F'(x) = f(x) and mathematically written as  $\int f(x) dx = F(x) + c$ Where "*c*" is constant of integration. Where "*c*" is constant of integration. **Definite Integral:** If F'(x) = f(x) then definite integral is defined as  $\int_{a}^{b} f(x) dx = \int_{a}^{b} F'(x) dx = [F(x)]_{a}^{b} = F(b) - F(a)$ . **Fundamental Theorem Of Calculus:** IF f(x) is continuous on  $[a,b]^{a}$  and F(x) is anti-derivative of f(x) then  $\int_{a}^{b} f(x) dx = F(b) - F(a)$ . Properties Of Definite Integral: (i)  $\int_{-\infty}^{\infty} f(x) dx = -\int_{-\infty}^{a} f(x) dx$  (ii)  $\int_{-\infty}^{\infty} f(x) dx = \int_{-\infty}^{\infty} f(t) dt$ . P.T.O Graphical Meaning Of Definite Integral: Graphical meaning of definite integral is area under the curve. **Compiled By: Muzzammil Subhan** Contact No: 0300-7779500 Website: www.narowalpk.com M.Phil. Math (Minhaj University Lahore) Email: info@narowalpk.com M.Sc. Math (Quaid-i-Azam University, Islamabad) M.Ed. (University of Sargodha), B.Sc., B.C.S. & PGD-IT

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Chapter No. <4> Median: Line segment joining one vertex of a triangle to the mid point of an opposite side of triangle is called median. Isosceles Triangle: A triangle having two sides are equal is called isosceles triangle. Equilateral Triangle: A triangle having all sides are equal is called equilateral triangle. Collinear Points: Points lying on same line are called collinear points. Trapezium: A quadrilateral having two parallel sides and two non parallel sides is called trapezium. Inclination Of A Line: The angle made by a line with positive x-axis in anti clock wise direction is called inclination of line. Declination Of A Line: The angle made by a line with positive x-axis in clock wise direction is called declination of line. Slope or Gradient: The measure of steepness ( لأهلوان ) is called slope or gradient. Centroid: The point of concurrency of medians is called centroid. BCSA Ortho Centre: The point of concurrency of altitudes of the triangle is called ortho centre. **Circum Centre:** The point of concurrency of right bisectors of the triangle is called circum centre. Chapter No. <5> Problem Constraint: Each linear inequality that related to certain problem of everyday life is called problem constraint. Decision Variable: The variable used in system of linear inequalities relating with the problem are called decision variable. Feasible Region: The solution region of an inequality restricted to first quadrant is called feasible region. Feasible Solution: Each point of feasible region is called feasible solution of system of linear inequality. Feasible Solution set: Set of all feasible solution of the system of linear inequality is called feasible solution set. Linear Programming: Mathematical techniques in which we get maximize or minimize value of variables of linear function is called linear programming. **Objective Function:** A function which is to be maximized or minimized is called objective function. **Optimal Solution:** The feasible solution which maximizes or minimizes the objective function is called optimal solution. Corner Points: Corner points of solution region are called vertex or corner point. Theorem Of Linear Programming: The theorem of linear programming state that optimal solution of objective function occurs at corner points of feasible region. Chapter No. <6> Cone: A solid figure generated by a straight line passing through a fixed point and revolving about a fixed line is called cone. Nappes: Two parts of cone are called nappes. Circle: "A set of all points in a plane which are equidistant from a fixed point is called circle." The fixed point is called centre and fixed distance is called radius of circle. Point Circle: A circle whose radius is zero is called point circle. Parabola: "A set of all points in a plane which are equidistant from fixed point and fixed line." The fixed point is called focus and fixed line is called directrix of parabola. Ellipse: A set of all points in a plane such that distance of each point from a fixed point bear a constant ratio less then one to the distance from a fixed line. Hyperbola: A set of all points in a plane such that distance of each point from a fixed point bear a constant ratio greater then one to the distance from a fixed line. Chapter No. <7> Scalar: A quantity which has magnitude only is called scalar. E.g. time, speed, area, volume, heat and work. Vector: A quantity which has both magnitude and direction is called vector. E.g. velocity, acceleration, momentum and force. Unit Vector: A vector whose magnitude is one is called unit vector. Null or Zero Vector: A vector whose magnitude is zero is called null or zero vector. Position Vector: A vector whose initial point is at origin "O" and terminal point is at point "P" is called position vector of point "P". Coplanar Vectors: The vectors lying in the same plane are called the coplanar vectors. **Parallel Vectors:** Two vectors  $\vec{a}$  and  $\vec{b}$  are said to be parallel if  $\vec{a} = k\vec{b}$  or  $\vec{b} = k\vec{a}$  where k is any scalar number. **Perpendicular or Orthogonal Vectors:** Two vectors  $\vec{a}$  and  $\vec{b}$  are said to be Perpendicular if  $\vec{a}.\vec{b}=0$ . State Parallelogram Law Of Vector Addition: The resultant of two vectors acting along the sides of parallelogram is the diagonal of the parallelogram. **Compiled By: Muzzammil Subhan** Contact No: 0300-7779500 M.Phil. Math (M.U. L.), M.Sc. Math (Q.A.U. Islamabad), M.Ed., B.Sc., B.C.S. & PGD-IT Website: www.narowalpk.com

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